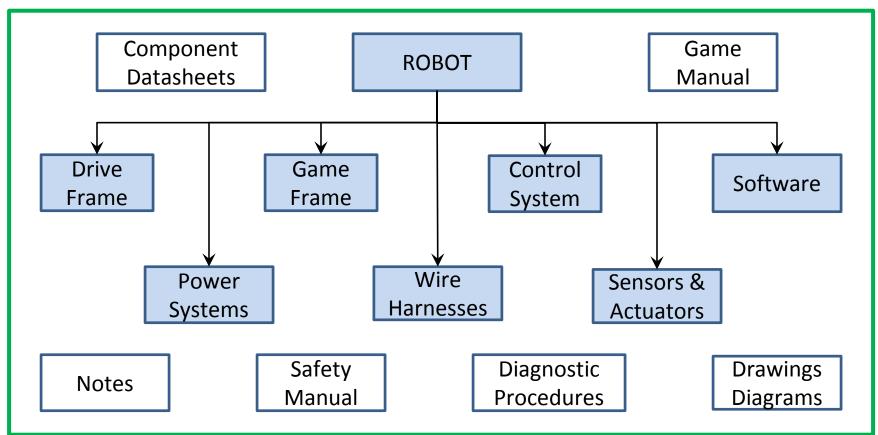


Robot Parts



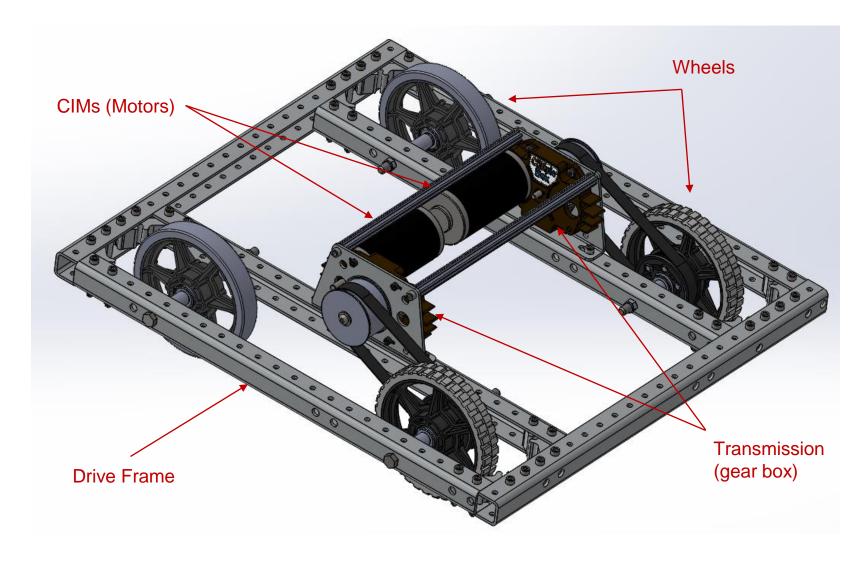
Robot Binder





Drive Frame & Power System Assembly

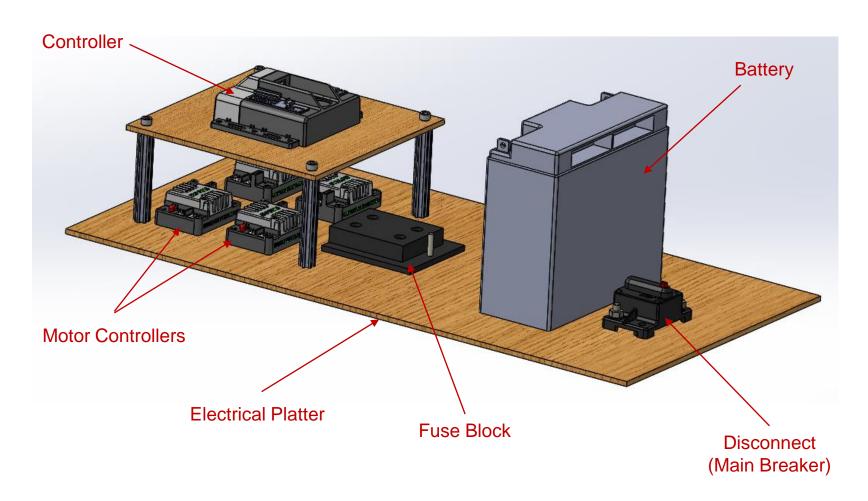






Electrical Platter (Controller, Battery & Power Distribution)







VEX Control System

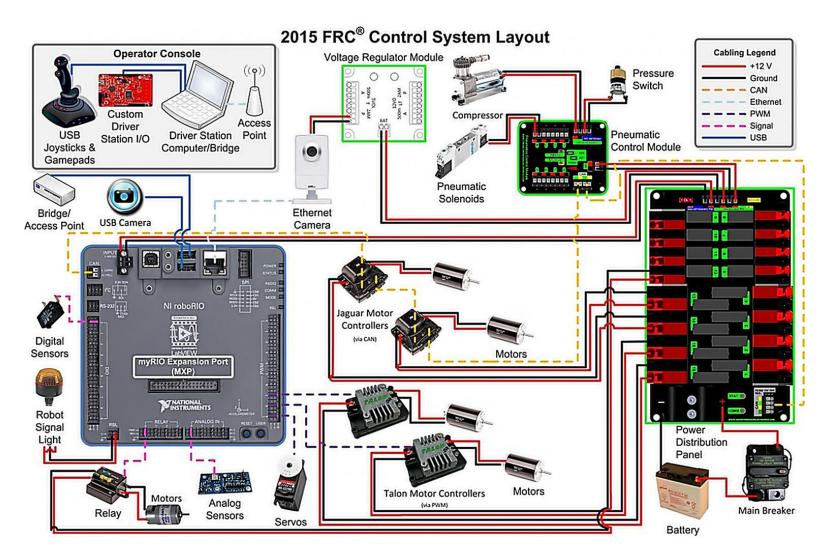






New FRC Control System



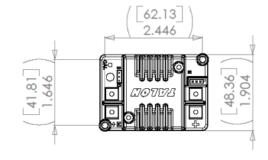


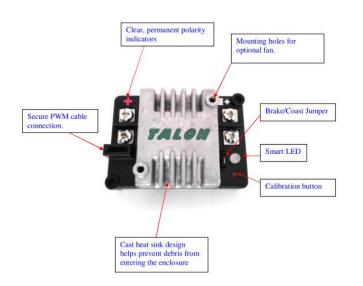


Motor Drivers









Insert PWM cable into housing

Letter 'B' should be aligned with the black wire of the pwm cable



Input voltage	6-28 VDC
Continuous current	60 A
Peak current	100 A
Input PWM signal	1-2 ms @ 333 Hz
Input resolution	10-bit (1024 steps)
Output resolution	10-bit (1024 steps)
Output switching frequency	15 kHz



Sensors







Line Trackers

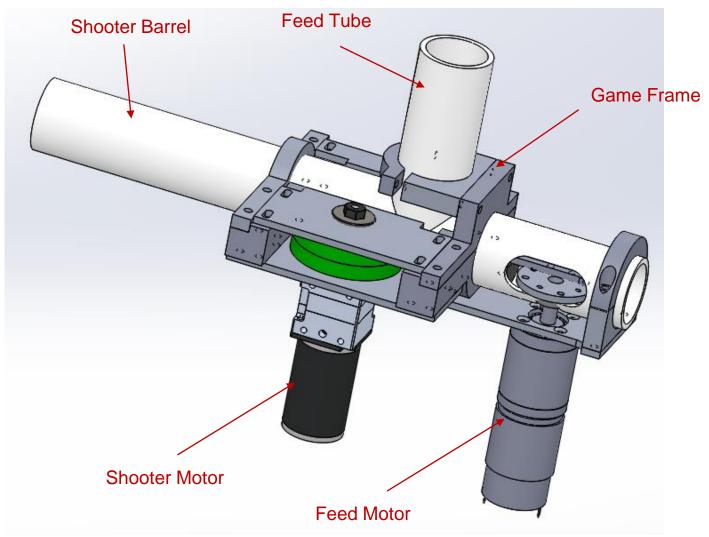
Must be 1/8" from Target

Push Buttons



Ping-Pong Shooter Assembly







Y1 Robot Full Assembly



